

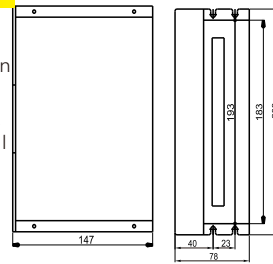
110 130 closed loop stepping driver 3LS2280

Product Description

Based on ARM new 32-bit DSP processing chip platform, the internal PID current control algorithm design, with excellent performance. The built-in micro-segmentation technology and the automatic tuning function of the power-on parameter make the driver have the characteristics of low noise, low vibration, low heat generation and high-speed high torque output. In addition, the patented three-phase demodulation algorithm can give full play to the low-speed resonance and small torque ripple characteristics of the phase stepping motor, and can be well adapted to applications requiring higher stability.

- Pulse mode: single pulse/ CW/CCW pulse
- Signal level: 5V/24V separate wiring, simple and practical, strong anti-interference ability.
- Typical applications: potting machines, engraving machines, cutting machines, laser equipment, CNC machine tools, automatic equipment and so on. The application effect is particularly good in a device where the user desires high speed and small noise.

install dimensions



Drive function description

Drive function	Operating Instructions
Microstep subdivision setting	SW5-SW8 four dial codes are used to select a total of 16 files of microsteps. When the user sets the micro step, driver should be stopped first. For detailed microstep subdivision settings, please see the drive panel description.
Output current setting	SW1-SW3 three dial switches are used to select a total of 8 output currents. For the specific output current setting, please see the driver panel description.
Pulse smoothing filter	The SW4 dial code is used to select the pulse smoothing function of the drive, the off means the off function, and on means the function is turned on
Pulse form selection	SW9 dial code is used to select the pulse form, off: pulse + direction ON : CW/CCW
Signal interface	PUL+ and PUL- are the positive and negative ends of the control pulse signal; DIR+ and DIR- are the positive and negative ends of the direction signal; ENA+ and ENA- are the positive and negative ends of the enable signal; ALM+ and ALM- are the positive and negative terminals of the alarm output signal; PLC control only needs to connect +24V, Pul- DIR three lines.
Encoder interface	EB+ and EB- are encoder B direction signals; EA+ and EA- are encoder A direction signals; VCC and GND are encoder power interfaces.
Motor interface	U, V, W butt the motor windings U, V, W, Arbitrarily swapping two of the three winding wires can change the direction of the motor., PE ground wire.
Power interface	The working voltage range is recommended for AC 110-230V. It is recommended to add a filter (EMI FILTER) before the power supply circuit.
LED	The driver has two indicators, red and green. The green light is the power indicator. The green light flashes after the driver is powered on. The red light is the fault indicator. The red light flickers when there is a fault in the gear and the encoder is misaligned. After the fault is cleared, the red light goes out. When an alarm occurs on the drive, it must be powered on again to clear the fault.

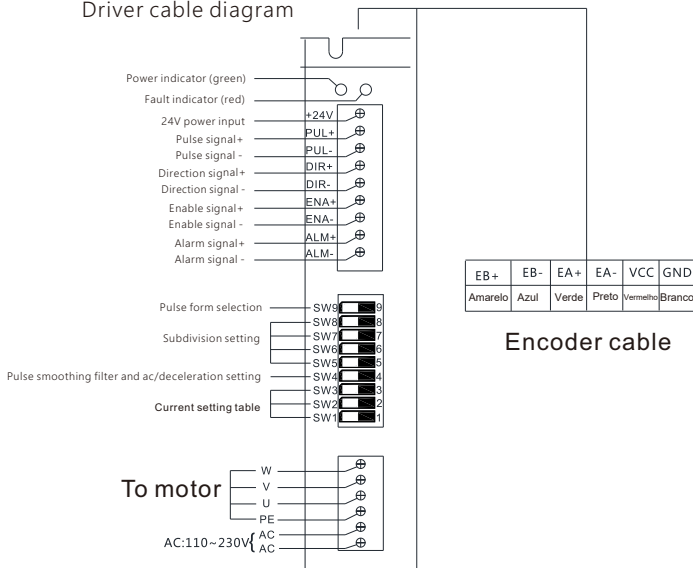
Installation Notes

Dimensions: 183 * 144 * 48mm, mounting hole spacing 156mm. Can be horizontal or vertical installation, but it should be close to the metal cabinet for better cooling

Driver operating status LED indication

LED status	Drive status
Green flashing	The driver is working properly (pulse input flashes faster)
1 green, 1 red	Drive overcurrent
1 green, 2 red	The code wheel is reversed or there is no code dial (you can change the parameter NO.15)
1 green, 3 red	Position error (closed loop)
1 green, 4 red	IPM Alarm
1 green, 5 red	ADC hardware error

Driver cable diagram



Output current peak	Output current Rms	SW1	SW2	SW3
3.9A	depend by PA5 parameter	on	on	on
5.0A	3.6A	off	on	on
6.3A	4.5A	on	off	on
7.6A	5.4A	off	off	on
8.7A	6.2A	on	on	off
9.8A	7.0A	off	on	off
11.2A	8.0A	on	off	off
12.6A	9.0A	off	off	off

Microstep subdivision setting

Steps / Turn	SW5	SW6	SW7	SW8
200	on	on	on	on
400	off	on	on	on
600	on	off	on	on
800	off	off	on	on
1000	on	on	off	on
1200	off	on	off	on
2000	on	off	off	on
3000	off	off	off	on
4000	on	on	on	off
5000	off	on	on	off
6000	on	off	on	off
10000	off	off	on	off
12000	on	on	off	off
20000	off	on	off	off
30000	on	off	off	off
8000	off	off	off	off